The work-from-home train driver? Remotely driving a train on the Betuweroute



06/06/2023 - RailTech Belgium

Introduction OTIV

OT\V



HQ Ghent, Belgium (EU)

Founding 02/2020

Team 15

Legal entity OTIV B.V.

Mission

OTIV aims to increase the safety and efficiency of rail by teaching rail vehicles to drive autonomously in complex environments

Customers, tests and pilots



Founders

Niels Van Damme (MSc. Automation Engineering, UGent): Co-founder and Tech lead Sam De Smet (MSc. Business Engineering, UGent) : Co-founder and Business lead

Partners





Our beliefs

Billions are invested in long term mobility solutions ...

... to tackle problems that rail already solves







EV (Car & truck)

Hyperloop

Carbon neutral aircrafts



Low CO2 emissions

CO₂



High capacity



Existing network and infrastructure

Developing the underlying tech for autonomy



- OTIV Confidential -

The road to autonomous goes over ADAS and R/C





Assistance System for Industrial Shunting OTIV.TWO



Advanced Driver Assistance System

OTIV.THREE



Remote Control Center OTIV.FOUR



Perception for Full Self-Driving (GoA4)

Why remote operation?







Back-up system for full autonomy

Improve driver efficiency

Increase the time spent actually driving

Increase asset utilization

Optimize fleet and network utilization

Benefits for freight, passenger, urban and industrial rail

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OTIV.ONE: Enabling remote operation for shunting



OTIV.THREE: Enabling remote operation for mainline



Remote Operation Center



- Supervision & Control center has a supervision desk and multiple control desks
- Onboard system directly connects to TCMS (ETCS and ATO if existant)
- Train control adapter receives and transmits commands between ATO/Control center and TCMS
- Non-intrusive system as the train can still be operated from the cabin

The project: ATO and R/C over Betuweroute in NL



- Essential rail freight route between German Ruhrgebiet and Port of Rotterdam
- Fenced area (acoustic barrier) without level crossings
- Protected by ETCS Level 2
- ATO GoA2 combined with R/C in operational trials in 2025
- Joint project of OTIV with partners Mobility42 (NL) and Rail Systems Engineering (CH)



Challenges and criteria for success

Human factors

Train integration

1-on-1 replication of the current driver cab, or development of a new driving experience?



Integration of On-Board control unit into TCMS / ATO / ETCS systems to be standardized on European level



Derogation / homologation

Safety for operational trails (derogation) and future full operational use (homologation)



What's next? Combining R/C with perception to achieve GoA4

Object segmentation



Object detection



Signaling detection



Rail segmentation



Lidar 3D clustering



3D vector space



What's next?



OTV Thank you!

Sam De Smet Co-founder <u>sam@otiv.ai</u>